Positioner Controller, simultaneous

AL-4164

The AL-4164 programmable positioner controller offers real-time control of positioning subsystems used in near-field and far-field antenna measurement systems. This controller may be configured to drive planar scanners and general purpose far-field positioners that are encoder-based or involve simultaneous motion.



Series Overview

Model	AL-4162	AL-4164	
Horsepower	Up to 1/3	Up to 1.25	
Number of Axes	2	4	

Applications

- Near-Field & Far-Field Antenna Measurements
- Encoder-Based Positioners & Scanners
- Light, Medium & Heavy Duty Positioning Subsystems

Product Highlights

- Simultaneous Control Up to 4 Axes
- 4 Independent PWM Channels
- Factory-Configurable Armature Output Voltage (24, 48 or 90 VDC)
- Built-In Power Control Unit (PCU)
 Absolute & Incremental Encoder Support
- Brush & Brushless Motor Support
- 8 TTL I/O Lines for Auxiliary Component Control
- User-Friendly Axis Configuration
 Software
- Dynamic Density Control (DDC)
- Communication to Host PC Supported by LAN, RS-232 & CAN Bus



Front Panel

Controls

- AC Power On/Off
- Axis Select
- Direction/Speed
- Coarse & Fine
- Remote/Local Control (BUS/PANEL)
- Emergency Stop (E-Stop)

Displays & Indicators

- Axis Position
- Limit Indicators
- Homing Status
- Homing Completed

Position Sensors

Axis-Independent Position Sensor Selection

Incremental Encoder & Absolute Encoder (EnDat[®])

Velocity Sensors

Axis-Independent Velocity Sensor Selection

Incremental Encoder & Tachometer

Closed Loop Motion Control Algorithms

- User Selectable PID or PIV Motion Control Filters
- Dynamic Braking
- Comprehensive Motion Profiles Velocity, Parabolic Ramping, S-Curve & Acceleration/Deceleration
- Single or Dual Feedback Encoders
- 3 Sets of Control Filter Scheduling
 - In-Motion
 - In-Settling
 - In-Position
- BEMF Feedback Circuits

Data Recording

- Data Recording Buffer Up to 100,000 Points
- Simultaneous Recording Up to 10 Vectors
- Record Up to 100,000 Vectors

Trigger Functions

- Supports Discrete Position Trigger Tables
- User Selectable Pulse Polarity
- User Selectable Pulse Width

Position Correction

- On-the-Fly Calculation Using Linear Interpolation
- Up to 40,000 Points (Can Be Divided 10,000 Points Per Axis)
- Mapping in User Selectable Units
- Inverse/Transpose Table
- Set Table Data Constant/Linear
- Load Table from File

Onboard Programming

Run Up to 10 Programs in Parallel

Supplied Accessories

Digital Documentation Set

- User Manual (Installation, Setup, Operation)
- Programming Reference Manual
- Software Setup Utility

Cables

- Cable, CAN, DB9 to RJ45
- Cable, RS-232, DB9 to RJ45
- AC Power Cord, IEC-320 (F) to Plug

Options

- Dopt. 001 PC-Based CAN-PCI Communication Card
- Dopt. 002 USB to CAN Adaptor
- Opt. 101 Additional Manual Set
- Dopt. 102 International Localization (Specify Country & Voltage)
- Standard Doptional

Specifications - AL-4160 Series Simultaneous Controllers

PARAMETER	POSITIONER MODEL		
	AL-4162		AL-4164
OPERATIONAL	'		
Front Panel Controls & Indicators	 AC Power On/Off Axis Select Coarse/Fine Speed Speed/Direction Control Local/Remote (Panel/Bus) Emergency Stop (Latching Panic Button) Digital Display w/ Limit Indicators 		
Correction Table Support (Geometrical Error)	Optional (Opt. 009)		
ELECTRICAL			
AC Input Power	 115/230 VAC +/- 10%, 47-63 Hz, single phase 10A rms @ 115 VAC 5A rms @ 230 VAC 		
Power Dissipation	0.7 KVA max		1.3 KVA max
Controlled Axes	2 simultaneous control		4 simultaneous control
EMI Filtering		MIL-STD-461/2, VDE 0871/3.68	
VDE Tests	 Leakage: 1,500 VAC Insulation: 500 VDC Bonding: 25 ADC 		
Speed Control Range (User-selectable)	 Coarse: 0-100% Fine: 0-18% 		
Supported Position Sensors	Incremental Encoder		 Selectable for each axis via setup utility Incremental Encoder EnDat[®] Absolute Encoder
Communication Links	• RS-232 (115,200 Baud Ra • CAN Bus	ite)	 RS-232 (115,200 Baud Rate) CAN Bus LAN
Trigger Functions		Trigger In/Out	
Data Take-Off Accuracy		Up to 29 bit resolution	
Supported Motion Control Filters	User Selectable PID/PIV		
Control Filter Scheduling	In-Motion & In-Settling		In-Motion, In-Settling, In-Position
Linked Axes		Axes 1 & 2 Only	
Load Inductance	No output choke required		
Maximum Motor Size	1/3 HP		3/4 HP
Motor Armature Supply (By Current)	• Axis 1: 4 Amps (avg.) • Axis 2: 4 Amps (avg.)		 Axis 1: 10 Amps (avg.) Axis 2: 10 Amps (avg.) Axis 3: 6 Amps (avg.) Axis 4: 6 Amps (avg.)

PARAMETER	POSITIONER MODEL	
	AL-4162	AL-4164

ELECTRICAL

Motor Armature Supply (By Voltage)	0 to \pm 90 VDC	Factory-Configurable Armature Output Voltage • 0 to \pm 90 VDC • 0 to \pm 48 VDC • 0 to \pm 24 VDC
Motor Armature Current Limiting	 1 to 5 amps Each Axis Selectable Via Internal Dip Switch 	 1 to 15 amps Each Axis Selectable Via Internal Dip Switch or Setup Utility
Motor Field Supply	110 VDC, 2 Amps Max Continuous	
Motor Driver Method	 Filtered Pulse Width Modulated (PWM) 32 kHz Nominal Switching Rate (above audible range) 	
Motor Direction	Bi-directional	
Dynamic Braking Supply	24 VDC, 2 Amps Max	
Compatible Local Control Units (LCU)	_	AL-4146-2L SeriesAL-4188 Series

PHYSICAL

Dimensions	 19.0 in (48.3 cm) Width 3.5 in (8.9 cm) Height 15.0 in (38.0cm) Depth 	 19.0 in (48.3 cm) Width 7.0 in (17.8 cm) Height 19.5 in (49.4 cm) Depth
Weight	33 lbs (15 kg)	70.4 lbs (31.9 kg)

ENVIRONMENTAL

Operating Temperature	32° to 122° F (0° to 50° C)
Storage Temperature	- 4° to 167° F (- 20° to 75° C)
Relative Humidity	90%

